

# Industrial networks



## Component

École Nationale  
Supérieure  
d'Électrotechnique  
d'Électronique  
d'Informatique  
d'Hydraulique  
et des  
Télécommunications

## In brief

- > **Ametys Code:** N8EE17B
- > **Open to exchange students:** Yes

## Presentation

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### Objectives

This module presents the specific features of network architectures in the context of applications that must meet time constraints. It draws on a set of significant examples from different application contexts, in particular the automotive, aeronautics, and space industries.

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### Description

Shared communication architectures have been used since the 1980s for real-time applications, replacing dedicated links, which were far too costly in terms of cabling and did not scale. Initially, fieldbus-type solutions, dedicated to specific application contexts, became the norm. These solutions control communication latencies but often offer limited throughput. They are therefore gradually being replaced by real-time Ethernet solutions, which offer much higher throughput and better system integration into their environment. The module is structured as follows.

- We introduce the general issues surrounding real-time communications and the different communication paradigms used.
- We study Controller Area Network (CAN), the associated temporal analysis methods, and protocol developments.

- We study the Airborne Switched Ethernet (AFDX) network with a particular focus on the worst-case analysis implemented by manufacturers.
- We highlight the problems posed by sharing a real-time Ethernet network between flows with different levels of criticality. We present the Ethernet TSN solution.
- We present the Mil-Std-1553 and Spacewire technologies used in the space sector.